Transforming Linear Algebra with GeoGebra

JMM 2014

January 17, 2014

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Note:

Copies of the draft applets presented at the JMM 2014 and the software to run them are at this location:

https://www.dropbox.com/sh/gff2xggpe815rgg/sy-KbOK_oy

Please look at READ ME file to run the software

If you are interested in getting these applets and the others being developed, have comments on improving them, and/or suggestions on topics you want to see covered, please contact me at my email address:

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This work is part of the:



NSF DUE-TUES Grant Award 1141045 (Sep. 1, 2012 – Aug. 31, 2015)

Transforming Linear Algebra Education with GeoGebra Applets

James D. Factor (PI) ; Susan Pustejovsky (Co-PI) Alverno College

GOAL:

Deepen understanding of linear algebra concepts

- Actively engage the student in the *geometric*, *algebraic*, and *numeric* perspectives of the concept
- Through interactive use of 2D and 3D applets
- Enhancing problem solving skills

Each Applet Package includes

- instructional support and
- a STEM application.



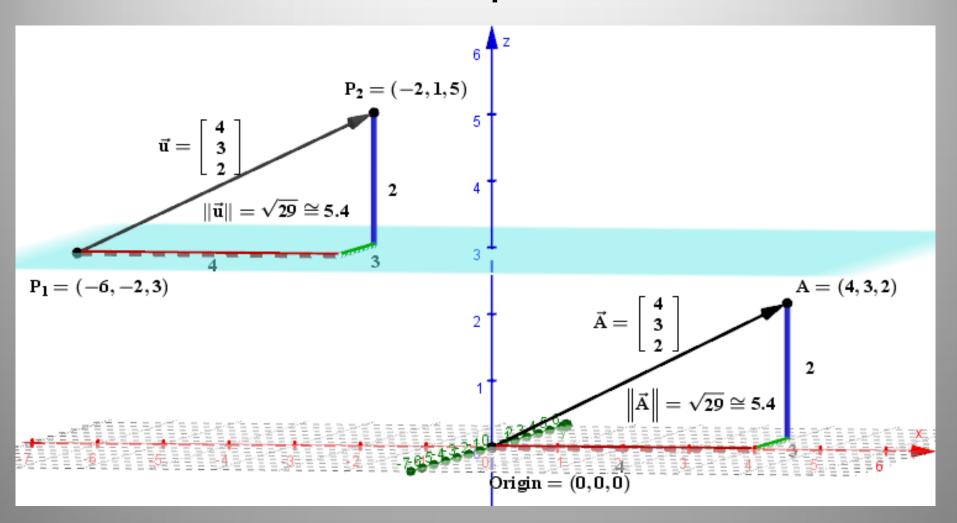


<u>Vector Package</u>		12 Linear Algebra Packages		GeoGebra 5.0 Beta
	Sequence 1: Vectors	Sequence 2: Linear Systems of Equations	Sequence 3: Matrices	Sequence 4: Vector Spaces
Level 1	<u>Vector Package</u> Points vs Vectors Addition/Subtraction Scalar Product Commutative & Associative Properties Linear Combinations	<u>Views of Linear</u> <u>Systems Package</u> Matrix View Row View Column View	<u>Matrix Package</u> Matrix Operations Matrix Properties Linear Independence Transpose	<u>Vector Spaces Package</u> Null Spaces Row Spaces Column Spaces Linear Transformations
Level 2	<u>Coordinate Grid Package</u> Coordinate Grids Change of Basis Linear Independence Linear Combinations	<u>Solving Linear Systems</u> <u>Package</u> Direct Methods Echelon Forms Solution Sets of Linear Systems of Equations Spanning Sets Linear Independence	<u>Matrix Inverse</u> <u>Package</u> Inverse of a Matrix Determinants Properties of Invertible Matrices Gauss-Jordan Method	<u>Spanning Spaces Package</u> Linearly Independent Sets Basis, Rank Dimensions of a Vector Space Vector Subspaces Spanning Spaces in R ² and R ³ Coordinate Systems (Matrix of Transposition)
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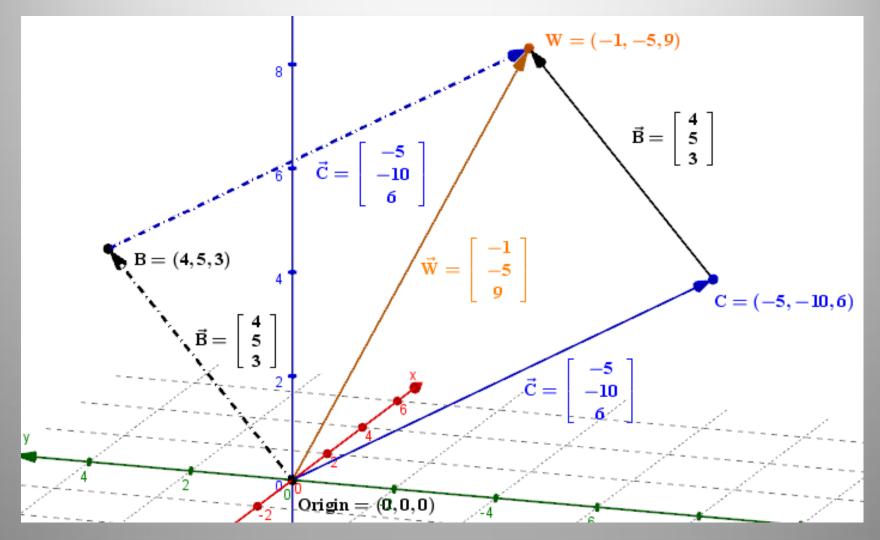
Vectors Sequence 1 (Fundamental Level 1) - Vector Package Sample







Adding Vectors, showing Commutative Property in 3D

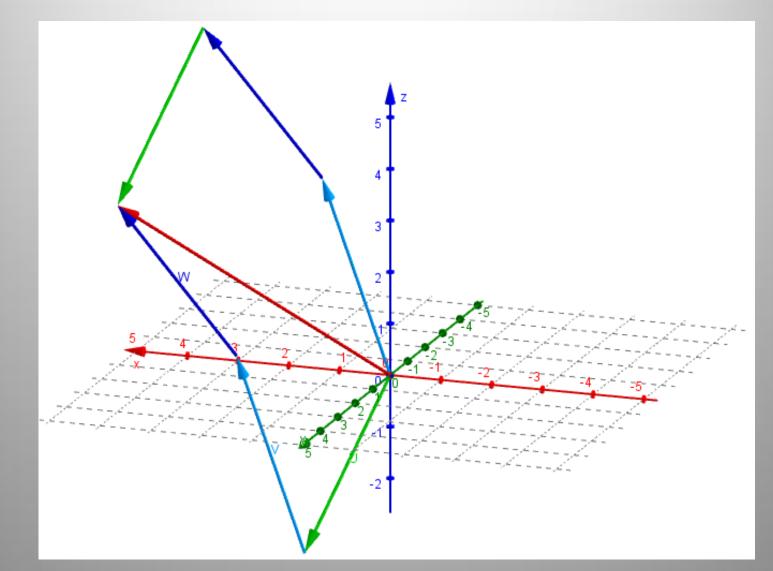




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Associativity of Vectors – 3D



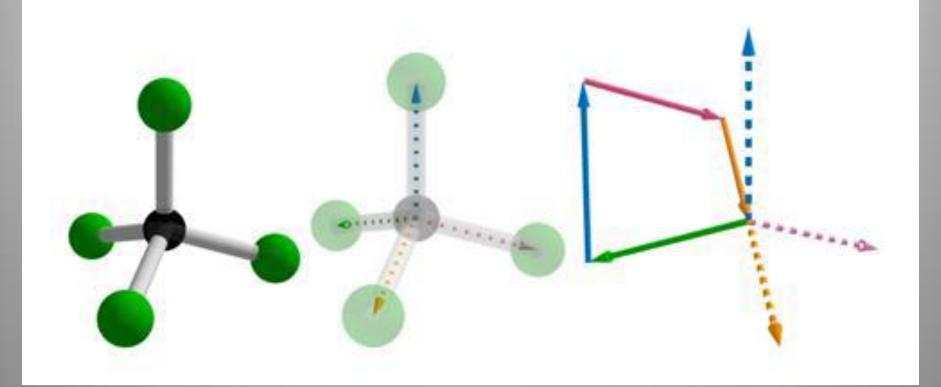


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STEM – Application

3D Application to CCI4: Using the Addition of Vectors







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Vector Sequence 1 (Intermediate Level 2) -Coordinate Grid Package -- Sample

Overview:

Coordinate Grid Package 2D - (S1L2) – Exploring new coordinate systems in R²

This applet involves change of coordinate systems in R² and visualization of linear combinations of vectors.

Student Learning Goals:

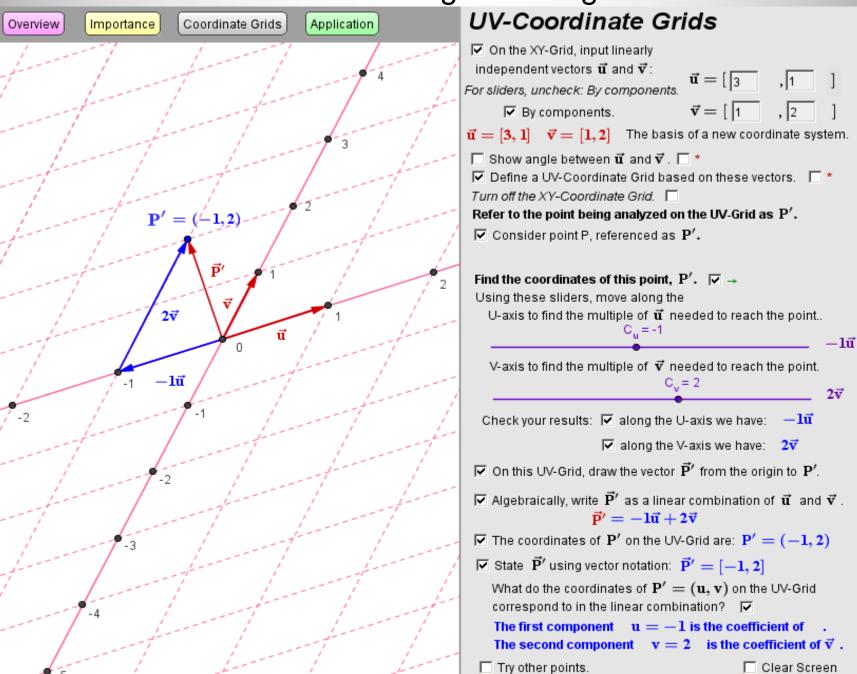
In this activity, students will:

- Explore the geometric, algebraic, and numeric meaning of a linear combination of vectors.
- Visualize a coordinate system in two dimensions based on two arbitrary linearly independent vectors.
- Identify the basis vectors of any two-dimensional coordinate system.
- Express coordinates of any point in the plane in terms of standard and non-standard coordinate systems.
- Develop facility with geometric imagination about alternate coordinate systems.
- Understand the geometric and algebraic similarities and differences of describing a point or a vector in different coordinate systems.
- Develop facility to write vectors as linear combinations of other vectors no matter what the coordinate system.
- Make conjectures about describing points and basis vectors in different coordinate systems and test them.





Coordinate Grid Package - Change of Basis



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S2L2 – Solving Linear Systems Package

Example: Find the intersection of the planes x + 2y - z = 3 and 2x + 3y + z = 1. The normal to the first plane is [1, 2, -1]The normal to the second plane is [2, 3, 1]

What do these two normals tell us about whether these planes intersect?

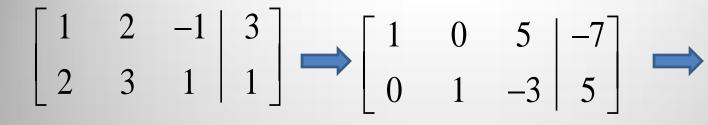
The points that lie on the intersection of the two planes correspond to the points in the solution set of the system

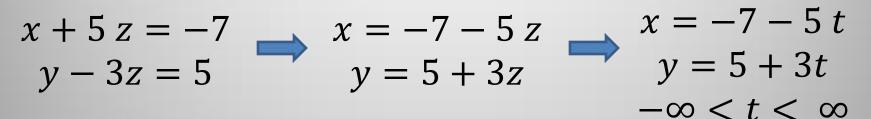
$$x + 2y - z = 3$$
$$2x + 3y + z = 1$$

We can solve using the Gauss-Jordan method.







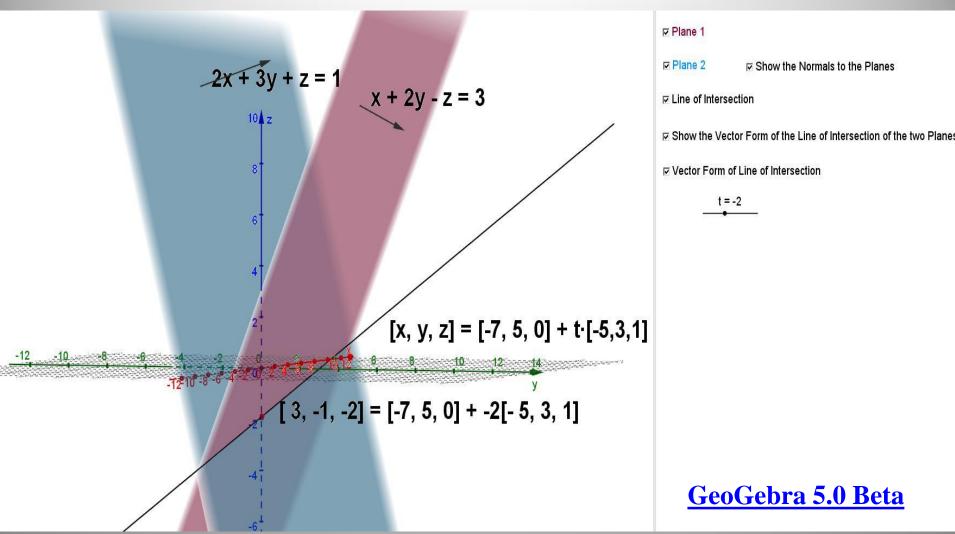


⇒ In vector form: $\begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} -7 \\ 5 \\ 0 \end{bmatrix} + t \begin{bmatrix} -5 \\ 3 \\ 1 \end{bmatrix}$ But what is this geometrically?









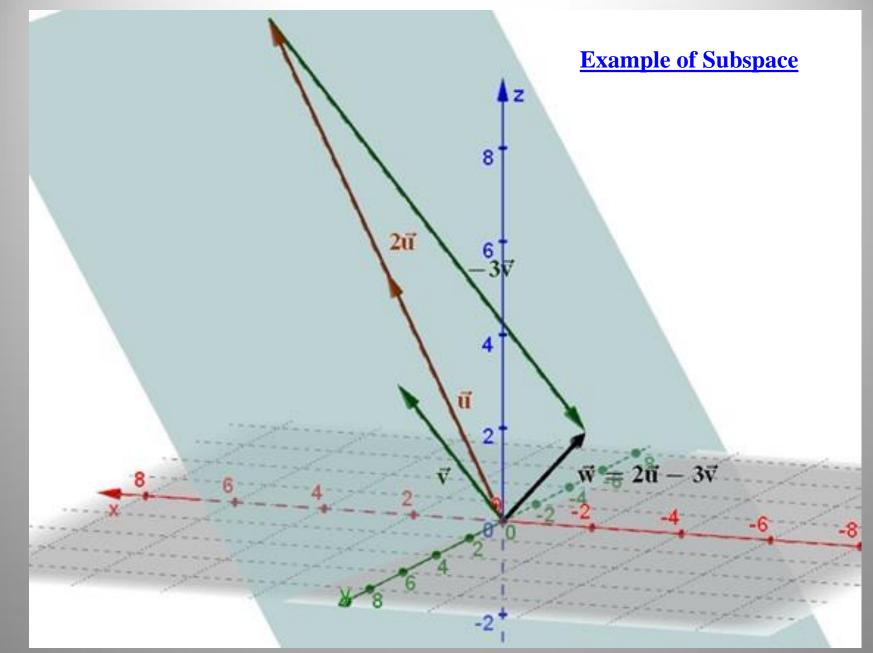




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Slide not in JMM 2014 Presentation but possibly of interest

