

Name: Solutions

Problem	T/F	1	2 / 3 / 4 / 5	Total
Possible	50	24	26	100
Received				

DO NOT OPEN YOUR EXAM UNTIL TOLD TO DO SO.**You may use a 3 x 5 card of notes, both sides.****FOR FULL CREDIT, SHOW ALL WORK RELATED TO FINDING EACH SOLUTION.****PEANUTS** /Charles Schulz

/50 T/F. Answer the following 25 True/False questions. Each question is worth 2 points. Note: "True" means *always true* or *necessarily true*. "False" means that it may be true some times or under some circumstances, but not always or not necessarily. No explanation is necessary whether true or false.

- (T) F If U is square and an orthogonal matrix (i.e., if $U^T U = I$), then it is also true that $U U^T = I$.
 $\uparrow U^T \text{ is } U^{-1}$
- (T) F If $\vec{x}$ is orthogonal to $\vec{u}$ and $\vec{v}$, then $\vec{x}$ is orthogonal to $\vec{u} - \vec{v}$.
- (T) F Given a subspace W of R^n , every vector $\vec{y} \in R^n$ can be written as $\vec{y} = \vec{z}_1 + \vec{z}_2$ where $\vec{z}_1 \in W$ and $\vec{z}_1 \cdot \vec{z}_2 = 0$.
- (T) F If $\|\vec{u} + \vec{v}\|^2 = \|\vec{u}\|^2 + \|\vec{v}\|^2$, then $\vec{u}$ and $\vec{v}$ are orthogonal.
- (T) F For $\vec{u}, \vec{v} \in R^3$, where $S = \text{span}\{\vec{u}, \vec{v}\}$ and $\dim S = 2$, then S is a plane and $S^\perp$ is the line perpendicular to S that passes through the origin.
- T (F) Every orthogonal set of vectors is linearly independent.
 $\hookrightarrow \text{non-zero}$
- T (F) Every linearly independent set of vectors is orthogonal.
- (T) F Given $\vec{y}$ and subspace W , the vector $\text{proj}_W \vec{y} - \vec{y}$ is orthogonal to W .
- (T) F Where $A = [\vec{a}_1 \ \vec{a}_2 \ \dots \ \vec{a}_n]$ and $\vec{x} = (x_1, x_2, \dots, x_n)$, in general, the best solution $\vec{x}$ to $A\vec{x} = \vec{b}$ is equivalent to the values of $x_1, x_2, \dots, x_n$ for which the linear combination $x_1 \vec{a}_1 + x_2 \vec{a}_2 + \dots + x_n \vec{a}_n$ is closest to $\vec{b}$.
- (T) F If the columns of $n \times n$ matrix A are orthonormal, then the solution $\vec{x}$ to $A\vec{x} = \vec{b}$ is $A^{-1}\vec{b}$.
 $\hookrightarrow \text{so linearly independent so } A^{-1} \text{ exists}$
- (T) F The least squares to solution to $A\vec{x} = \vec{b}$ is the vector $\vec{x}$ which minimizes $\|\vec{b} - A\vec{x}\|$.
- (T) F For two vectors $\vec{u}$ and $\vec{v}$ in R^4 , $\vec{u} \cdot \vec{v} = 0$ means the vectors are orthogonal.
- T (F) $\|\vec{u} - \vec{v}\| = \|\vec{u}\| + \|\vec{v}\|$.
 Not at all.

(T) F If $\vec{u}$ is in $\text{Col } A^T$ and if $\vec{v}$ is in $\text{Nul } A$, then it must be that $\vec{u} \cdot \vec{v} = 0$.

See Theorem 3, page 335.

T (F) If $W = \text{span}\{\vec{v}_1, \vec{v}_2\}$, then $\text{proj}_W \vec{u} = \frac{\langle \vec{u}, \vec{v}_1 \rangle}{\langle \vec{v}_1, \vec{v}_1 \rangle} \vec{v}_1 + \frac{\langle \vec{u}, \vec{v}_2 \rangle}{\langle \vec{v}_2, \vec{v}_2 \rangle} \vec{v}_2$.

True if $\vec{v}_1, \vec{v}_2$ are orthogonal.

(T) F It is possible for four non-zero vectors in $\mathbb{R}^5$ to be mutually orthogonal.

T (F) For any matrix A , the product $A^T A$ has an inverse.

If cols. of A are lin. ind. (which is typical)

T (F) $\text{Proj}_{\vec{a}} \vec{b} = \frac{\vec{b} \cdot \vec{a}}{\vec{a} \cdot \vec{a}} \vec{a}$.

(T) F If $\langle f, g \rangle = \int_0^1 f(t)g(t) dt$, then $\| -5f \| = 5\|f\|$.

T (F) $\left\{ \begin{bmatrix} 1 \\ 1 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \end{bmatrix} \right\}$ is an orthogonal basis for $\mathbb{R}^2$.

(T) F If A has orthonormal columns, then for any vectors $\vec{x}$ and $\vec{y}$ it is true that $(A\vec{x}) \cdot (A\vec{y}) = \vec{x} \cdot \vec{y}$. *See Theorem 7, page 343.*

T (F) Every matrix has a complete (linearly independent) set of orthonormal eigenvectors. *This would be nice. Example: $\begin{bmatrix} 1 & 1 \\ 0 & 1 \end{bmatrix}$ has one e-vector $\begin{bmatrix} 1 \\ 0 \end{bmatrix}$*

(T) F If A is invertible and has an eigenvalue of 1, then so does A^{-1} .

(T) F Each eigenvector of A is also an eigenvector of A^2 . $A\vec{v} = \lambda\vec{v} \Rightarrow A^2\vec{v} = A(A\vec{v}) = A(\lambda\vec{v}) = \lambda(A\vec{v}) = \lambda(\lambda\vec{v}) = \lambda^2\vec{v}$.

(T) F If $A = \begin{bmatrix} 1 & 3 & 5 \\ 2 & 4 & 6 \end{bmatrix}$ and $\vec{b} = \begin{bmatrix} 7 \\ 8 \end{bmatrix}$, then $\text{Proj}_{\text{Col } A} \vec{b} = \begin{bmatrix} 7 \\ 8 \end{bmatrix}$. *since cols. of A span $\mathbb{R}^2$.*

(T) F If $\vec{v}$ is an eigenvector of both A and B , then $\vec{v}$ is also an eigenvector of both AB and BA .

$AB\vec{v} = A(\lambda_B \vec{v}) = \lambda_B (A\vec{v}) = \lambda_B \lambda_A \vec{v}$
Same for BA .

$\vec{u}_1 \quad \vec{u}_2$

/24 1. Suppose matrix $U = \begin{bmatrix} 1/2 & 1/2 \\ 1/2 & -1/2 \\ 1/2 & 1/2 \\ 1/2 & -1/2 \end{bmatrix}$ and $\vec{b} = \begin{bmatrix} 1 \\ 1 \\ 1 \\ 0 \end{bmatrix}$, and $A = \begin{bmatrix} 1 & 1 \\ 1 & 5 \\ 1 & 1 \\ 1 & 5 \end{bmatrix}$.

Note that $\text{Col } U = \text{Col } A$ (since column 1 of A is twice column 1 of U , and column 2 of A is six times the column 1 of U minus four times column 2 of U).

/7 (a) Find the orthogonal projection of $\vec{b}$ onto $\text{Col } U$. Notice that the columns of U are orthonormal.

$$\text{Proj}_{\text{Col } U} \vec{b} = \frac{\vec{b} \cdot \vec{u}_1}{\vec{u}_1 \cdot \vec{u}_1} \vec{u}_1 + \frac{\vec{b} \cdot \vec{u}_2}{\vec{u}_2 \cdot \vec{u}_2} \vec{u}_2 = \frac{3}{2} \begin{bmatrix} \frac{1}{2} \\ \frac{1}{2} \\ \frac{1}{2} \\ \frac{1}{2} \end{bmatrix} + \frac{1}{2} \begin{bmatrix} \frac{1}{2} \\ -\frac{1}{2} \\ \frac{1}{2} \\ -\frac{1}{2} \end{bmatrix} = \begin{bmatrix} 1 \\ \frac{1}{2} \\ 1 \\ \frac{1}{2} \end{bmatrix}$$

/3 (b) Find $UU^T \vec{b}$.

not = I
since U
is not
square

$$= \text{Proj}_{\text{Col } U} \vec{b} =$$

/5 (c) Find the least squares solution $\hat{\vec{x}}$ to $U\vec{x} = \vec{b}$, and then find $U\hat{\vec{x}}$.

$$U^T U = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}, \quad U^T \vec{b} = \begin{bmatrix} \frac{3}{2} \\ \frac{1}{2} \end{bmatrix}$$

$$\text{So } \hat{\vec{x}} = (U^T U)^{-1} U^T \vec{b} = \begin{bmatrix} \frac{3}{2} \\ \frac{1}{2} \end{bmatrix}$$

$$\begin{bmatrix} \frac{1}{2} & \frac{1}{2} \\ \frac{1}{2} & -\frac{1}{2} \\ \frac{1}{2} & \frac{1}{2} \\ \frac{1}{2} & -\frac{1}{2} \end{bmatrix} \begin{bmatrix} \frac{3}{2} \\ \frac{1}{2} \end{bmatrix} = \begin{bmatrix} 1 \\ \frac{1}{2} \\ 1 \\ \frac{1}{2} \end{bmatrix}$$

/9 (d) Find the least squares solution $\hat{\vec{x}}$ to $A\vec{x} = \vec{b}$, and then find $A\hat{\vec{x}}$.

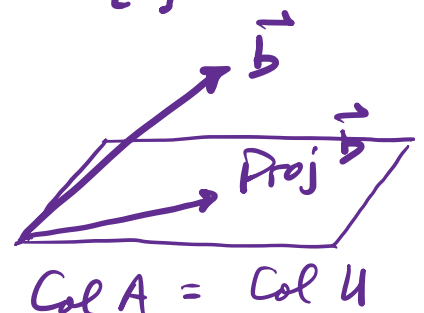
Same as above.

$$(A^T A)^{-1} = \begin{bmatrix} 4 & 12 \\ 12 & 52 \end{bmatrix}^{-1} = \frac{1}{4 \cdot 52 - 12 \cdot 12} \begin{bmatrix} 52 & -12 \\ -12 & 4 \end{bmatrix} = \frac{1}{16} \begin{bmatrix} 13 & -3 \\ -3 & 1 \end{bmatrix} \quad A^T \vec{b} = \begin{bmatrix} 3 \\ 7 \end{bmatrix}$$

$$\hat{\vec{x}} = (A^T A)^{-1} A^T \vec{b} = \frac{1}{16} \begin{bmatrix} 13 & -3 \\ -3 & 1 \end{bmatrix} \begin{bmatrix} 3 \\ 7 \end{bmatrix} = \frac{1}{16} \begin{bmatrix} 18 \\ -2 \end{bmatrix} = \begin{bmatrix} \frac{9}{8} \\ -\frac{1}{8} \end{bmatrix}$$

$$A \hat{\vec{x}} = \begin{bmatrix} 1 & 1 \\ 1 & 5 \\ 1 & 1 \\ 1 & 5 \end{bmatrix} \begin{bmatrix} \frac{9}{8} \\ -\frac{1}{8} \end{bmatrix} = \begin{bmatrix} 1 \\ \frac{1}{2} \\ 1 \\ \frac{1}{2} \end{bmatrix}$$

Same as above
since $\text{Col } A = \text{Col } U$.



/6 2. Where $\vec{x}_1 = \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}$, $\vec{x}_2 = \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix}$, use the Gram-Schmidt Process to find vectors $\vec{v}_1, \vec{v}_2$ so

that $\text{Span}\{\vec{v}_1, \vec{v}_2\} = \text{Span}\{\vec{x}_1, \vec{x}_2\}$ but where $\vec{v}_1 \cdot \vec{v}_2 = 0$.

$$\vec{v}_2 = \vec{x}_2 - \frac{\vec{x}_2 \cdot \vec{v}_1}{\vec{v}_1 \cdot \vec{v}_1} \vec{v}_1 = \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix} - \frac{6}{3} \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} = \begin{bmatrix} -1 \\ 0 \\ 1 \end{bmatrix}. \text{ Easy to see that } \vec{v}_1 \cdot \vec{v}_2 = 0.$$

/8 3. Given functions $f(t) = 1$ and $g(t) = t$, use the Gram-Schmidt Process to find two functions that are orthogonal under the inner product $\langle f, g \rangle = \int_0^1 f(t)g(t)dt$.

$$g - \frac{\langle g, f \rangle}{\langle f, f \rangle} f = t - \frac{\langle t, 1 \rangle}{\langle 1, 1 \rangle} 1 = t - \frac{\int_0^1 t \cdot 1 dt}{\int_0^1 1 \cdot 1 dt} \cdot 1 = t - \frac{1}{2}$$

$$\text{Could check that } \langle 1, t - \frac{1}{2} \rangle = \int_0^1 1(t - \frac{1}{2}) dt = 0.$$

$$\text{For the final two problems, } A = PDP^{-1} = \begin{bmatrix} 1 & -3 \\ 1 & 1 \end{bmatrix} \begin{bmatrix} 5 & 0 \\ 0 & 3 \end{bmatrix} \begin{bmatrix} 1 & -3 \\ 1 & 1 \end{bmatrix}^{-1} = \begin{bmatrix} 3.5 & 1.5 \\ 0.5 & 4.5 \end{bmatrix}.$$

/6 4. The position $\vec{x}$ of a particle in a planar force field satisfies the equation $\frac{d\vec{x}}{dt} = A\vec{x}$.

Where $\vec{x}(0) = \begin{bmatrix} 7 \\ 11 \end{bmatrix}$, find the function/formula $\vec{x}(t)$ for the particle position at time t .

$$\vec{x}(t) = c_1 \begin{bmatrix} 1 \\ 1 \end{bmatrix} e^{5t} + c_2 \begin{bmatrix} -3 \\ 1 \end{bmatrix} e^{3t}$$

$$\begin{bmatrix} 7 \\ 11 \end{bmatrix} = \vec{x}(0) = c_1 \begin{bmatrix} 1 \\ 1 \end{bmatrix} + c_2 \begin{bmatrix} -3 \\ 1 \end{bmatrix} = \begin{bmatrix} 1 & -3 \\ 1 & 1 \end{bmatrix} \begin{bmatrix} c_1 \\ c_2 \end{bmatrix} \text{ since } e^{5 \cdot 0} = 1, e^{3 \cdot 0} = 1.$$

$$\Rightarrow \begin{bmatrix} c_1 \\ c_2 \end{bmatrix} = \begin{bmatrix} 1 & -3 \\ 1 & 1 \end{bmatrix}^{-1} \begin{bmatrix} 7 \\ 11 \end{bmatrix} = \frac{1}{4} \begin{bmatrix} 1 & 3 \\ -1 & 1 \end{bmatrix} \begin{bmatrix} 7 \\ 11 \end{bmatrix} = \begin{bmatrix} 10 \\ 1 \end{bmatrix}.$$

/6 5. The size of two competing populations $\vec{x}$ change according to $\vec{x}_{k+1} = A\vec{x}_k$.

Where $\vec{x}_0 = \begin{bmatrix} 7 \\ 11 \end{bmatrix}$, find the function/formulation for $\vec{x}_k$.

$$\vec{x}_k = c_1 \begin{bmatrix} 1 \\ 1 \end{bmatrix} 5^k + c_2 \begin{bmatrix} -3 \\ 1 \end{bmatrix} 3^k$$

with same c_1, c_2 as in 4.

Invertible Matrix Theorem for $n \times n$ matrix A

- | | |
|---|--|
| a. A is invertible. | o. $\dim \text{Col } A = n$, <i>i.e.</i> dimension of column space of A is n . |
| b. A is row equivalent to I . | p. $\text{rank } A = n$, <i>i.e.</i> rank of A is n . |
| c. A has n pivot positions. | q. $\text{Nul } A = \{\mathbf{0}\}$, <i>i.e.</i> nullspace of A is $\{\mathbf{0}\}$. |
| d. $A\mathbf{x} = \mathbf{0}$ has only trivial solution. | r. $\dim \text{Nul } A = 0$, the dimension of the null space of A is 0 . |
| e. Columns of A lin. independent. | s. A has n nonzero eigenvalues, <i>i.e.</i> 0 is not an eigenvalue of A . |
| f. Linear transf. $\mathbf{x} \rightarrow A\mathbf{x}$ 1-to-1. | t. $\det A \neq 0$. |
| g. $A\mathbf{x} = \mathbf{b}$ has at least one solution for each $\mathbf{b}$. | u. $(\text{Col } A)^\perp = \{\mathbf{0}\}$, <i>i.e.</i> orthogonal complement of column space of A is $\{\mathbf{0}\}$. |
| h. Columns of A span $\mathbf{R}^n$. | v. $(\text{Nul } A)^\perp = \mathbf{R}^n$, <i>i.e.</i> orthogonal complement of null space of A is $\mathbf{R}^n$. |
| i. Linear transf. $\mathbf{x} \rightarrow A\mathbf{x}$ onto. | w. $\text{Row } A = \mathbf{R}^n$, row space of A is $\mathbf{R}^n$. |
| j. There is C such that $CA = I$. | |
| k. There is D such that $AD = I$. | |
| l. A^T is invertible. | |
| m. Columns of A form basis for $\mathbf{R}^n$. | |
| n. Column space of A is $\mathbf{R}^n$. | |