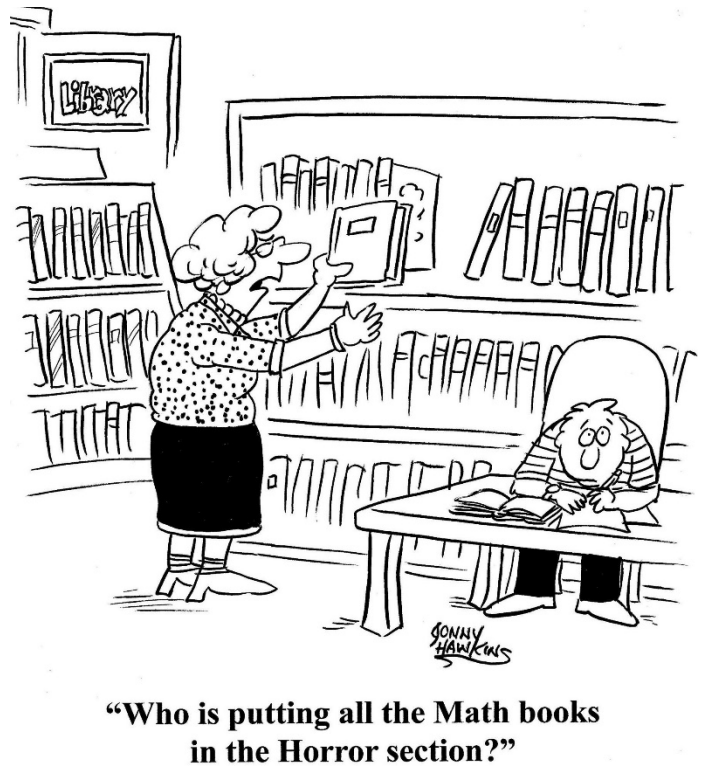
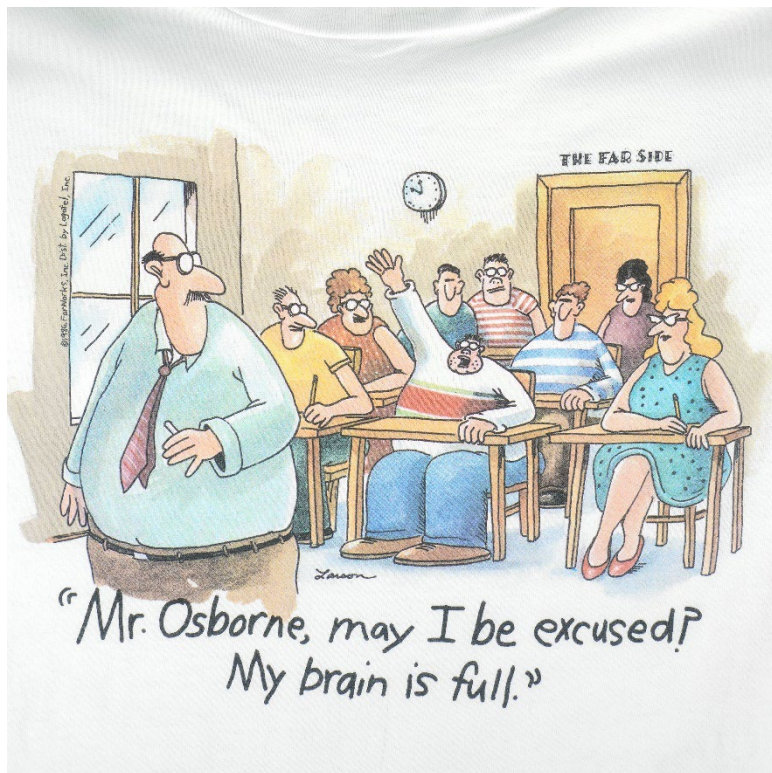


Name: Solutions

Problem	T/F	1 / 2	3	4 / 5	Total
Possible	50	15	15	20	100
Received					

YOU MAY USE A 3 X 5 CARD OF NOTES.

FOR FULL CREDIT, SHOW ALL WORK RELATED TO FINDING EACH SOLUTION.



50 points T/F. Answer the following 25 True/False questions. Each question is worth 2 points. Note: "True" means *always true* or *necessarily true*. "False" means that it may be true sometimes or under some circumstances, but not always or not necessarily. No explanation is necessary whether true or false.

- (1) T F If 4×5 matrix A has two pivot columns, then $\text{Col } A = \mathbb{R}^2$.
A 2-dim. subspace of \mathbb{R}^5 , but not \mathbb{R}^2 .
- (2) T F If $A\vec{v}_1 = \lambda_1\vec{v}_1$ and $A\vec{v}_2 = \lambda_2\vec{v}_2$ where \vec{v}_1 and \vec{v}_2 are eigenvectors of A and $\lambda_1 \neq \lambda_2$, then it must be that \vec{v}_1 and \vec{v}_2 are linearly independent.
- (3) T F For matrix A , if \vec{v}_1 is an eigenvector corresponding to eigenvalue λ_1 and \vec{v}_2 is an eigenvector corresponding to eigenvalue λ_2 , then $\vec{v}_1 - \vec{v}_2$ is an eigenvector corresponding to eigenvalue $\lambda_1 - \lambda_2$.
- (4) T F For 3×5 matrix A , $3 \leq \text{rank } A \leq 5$. *rank $A \leq \min(3, 5)$*
- (5) T F If a 5×5 ^{square} matrix A has rank 4, then $A\vec{x} = \vec{b}$ could have a unique solution for some right hand side \vec{b} . *$\Leftrightarrow A$ is "bad" \Rightarrow free variable
 \Rightarrow if there is a sol'n., then there are ∞ solns.*
- (6) T F If a 5×5 matrix A has rank 4, then $A\vec{x} = \vec{b}$ will have no solution for some right hand side \vec{b} and an infinite number of solutions for some other \vec{b} .
- (7) T F If a 5×5 matrix A has rank 4, then $A\vec{x} = \vec{b}$ will have an infinite number of solutions for some right hand side \vec{b} , no solution for some other right hand side \vec{b} , and a unique solution for yet another right hand side \vec{b} .
- (8) T F The area of the parallelogram with vertices of the origin, (1,3) and (2,1) is 5.
Abs. value of $\begin{vmatrix} 1 & 2 \\ 3 & 1 \end{vmatrix}$.

(9) T F For any $\vec{v}_1, \vec{v}_2, \vec{v}_3$ in R^5 , $\text{span}\{\vec{v}_1, \vec{v}_2, \vec{v}_3\}$ is a subspace of R^5 .

(10) T F $\begin{bmatrix} 5 \\ 5 \end{bmatrix}$ is in both the column space and the null space of $\begin{bmatrix} 3 & -3 \\ 3 & -3 \end{bmatrix}$.

(11) T F $\begin{bmatrix} 1 & 3 \\ 2 & 4 \end{bmatrix} \begin{bmatrix} 6 & 0 \\ 0 & 7 \end{bmatrix} \begin{bmatrix} 1 & 3 \\ 2 & 4 \end{bmatrix}^{-1} = \begin{bmatrix} 6 & 1 \\ 8 & 2 \end{bmatrix} \begin{bmatrix} 7 & 0 \\ 0 & 6 \end{bmatrix} \begin{bmatrix} 6 & 1 \\ 8 & 2 \end{bmatrix}^{-1}$.
Re-order e-vectors/values in $A = PDP^{-1}$

(12) T F For a 3×5 matrix, the dimensions of the row space and column space will be different.
Always = # pivots

(13) T F If $\{\vec{v}_1, \vec{v}_2, \vec{v}_3\}$ is a basis for R^3 , then the matrix $[\vec{v}_1 \vec{v}_2 \vec{v}_3]$ is invertible.
 \Leftrightarrow lin. ind. \Rightarrow \rightarrow

(14) T F If $\det A = 2$ and $\det B = -3$, then $\det(A + B) = -1$.

(15) T F $\det(A^T) = -\det A$.

(16) T F If $A\vec{x} = \vec{b}$, then \vec{x} is in the column space of A .
 *\uparrow
 \vec{b}*

(17) T F $\begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}$ is an eigenvector of matrix $\begin{bmatrix} a & b & c \\ c & a & b \\ b & c & a \end{bmatrix}$, no matter what a, b and c are.
 $\rightarrow = (a+b+c) \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}$

(18) T F The determinant of $\begin{bmatrix} 1 & 4 & 7 \\ 2 & 5 & 8 \\ 3 & 6 & 0 \end{bmatrix} \begin{bmatrix} 3 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 5 \end{bmatrix} \begin{bmatrix} 1 & 4 & 7 \\ 2 & 5 & 8 \\ 3 & 6 & 0 \end{bmatrix}^{-1}$ is 0.
det. is 0

and $\det ABC = \det A \cdot \det B \cdot \det C$.

(19) \textcircled{T} F If the determinant of $\begin{bmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \\ 0 & 0 & 0 \end{bmatrix}$ were 5 (it's actually not), then the determinant of $\begin{bmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \\ 5 & 7 & 9 \end{bmatrix}$ would also be 5. *Row 3 = Row 1 + Row 2 doesn't change det.*

(20) T \textcircled{F} If the determinant of $\begin{bmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \\ 0 & 0 & 0 \end{bmatrix}$ were 5 (it's actually not), then the determinant of $\begin{bmatrix} 0 & 0 & 0 \\ 4 & 5 & 6 \\ 1 & 2 & 3 \end{bmatrix}$ would also be 5. *Swapping rows changes sign +/- of det.*

(21) T \textcircled{F} If the determinant of $\begin{bmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \\ 0 & 0 & 0 \end{bmatrix}$ were 5 (it's actually not), then the determinant of $\begin{bmatrix} 10 & 20 & 30 \\ 40 & 50 & 60 \\ 0 & 0 & 0 \end{bmatrix}$ would be ~~50~~. *5 · 10 · 10.*

For the final four problems, V is a vector space, and vectors $\vec{v}_1, \vec{v}_2, \dots, \vec{v}_n$ come from V .

(22) \textcircled{T} F If $\{\vec{v}_1, \vec{v}_2, \dots, \vec{v}_n\}$ form a basis for V , then $\{\vec{v}_1, \vec{v}_2, \dots, \vec{v}_n\}$ is linearly independent.

(23) T \textcircled{F} If $\{\vec{v}_1, \vec{v}_2, \dots, \vec{v}_n\}$ is linearly independent, then $\{\vec{v}_1, \vec{v}_2, \dots, \vec{v}_n\}$ form a basis for V .

(24) \textcircled{T} F If $\text{span}\{\vec{v}_1, \vec{v}_2, \dots, \vec{v}_n\} = V$, then some subset of $\{\vec{v}_1, \vec{v}_2, \dots, \vec{v}_n\}$ is a basis for V .

(25) \textcircled{T} F If $\dim V = n$ and $\text{span}\{\vec{v}_1, \vec{v}_2, \dots, \vec{v}_n\} = V$, then $\{\vec{v}_1, \vec{v}_2, \dots, \vec{v}_n\}$ is linearly independent. *So $\{\vec{v}_1, \dots, \vec{v}_n\}$ is a basis for V , so*

- 5 points 1. If a 5×9 matrix A has rank 3, then:
- $$\begin{aligned} \dim \text{Row } A &= 3 \\ \text{rank } A^T &= 3 \\ \dim \text{Nul } A &= 9 - 3 = 6 \end{aligned}$$
- If a 9×5 matrix A has rank 3, then: $\dim \text{Nul } A = 5 - 3 = 2$
- If a 5×5 matrix A has rank 3, then: $\dim \text{Nul } A = 5 - 3 = 2$

- 10 points 2. Consider the probability matrix $A = \begin{bmatrix} 1/3 & 1/2 \\ 2/3 & 1/2 \end{bmatrix}$, which has eigenvectors $\begin{bmatrix} 1 \\ -1 \end{bmatrix}$ and $\begin{bmatrix} 3 \\ 4 \end{bmatrix}$ and corresponding eigenvalues $-1/6$ and 1 .

First, suppose that $\vec{x}_0 = \begin{bmatrix} 500 \\ 500 \end{bmatrix}$. Find \vec{x}_0 as a linear combination of $\begin{bmatrix} 1 \\ -1 \end{bmatrix}$, $\begin{bmatrix} 3 \\ 4 \end{bmatrix}$.

That is find $[\vec{x}_0]_B$ where $B = \left\{ \begin{bmatrix} 1 \\ -1 \end{bmatrix}, \begin{bmatrix} 3 \\ 4 \end{bmatrix} \right\}$. Don't just guess—show your work.

$$\begin{aligned} \begin{bmatrix} 500 \\ 500 \end{bmatrix} &= c_1 \begin{bmatrix} 1 \\ -1 \end{bmatrix} + c_2 \begin{bmatrix} 3 \\ 4 \end{bmatrix} = \begin{bmatrix} 1 & 3 \\ -1 & 4 \end{bmatrix} \begin{bmatrix} c_1 \\ c_2 \end{bmatrix} \\ \Rightarrow \begin{bmatrix} c_1 \\ c_2 \end{bmatrix} &= \begin{bmatrix} 1 & 3 \\ -1 & 4 \end{bmatrix}^{-1} \begin{bmatrix} 500 \\ 500 \end{bmatrix} = \frac{1}{1 \cdot 4 - (-1)(3)} \begin{bmatrix} 4 & -3 \\ 1 & 1 \end{bmatrix} \begin{bmatrix} 500 \\ 500 \end{bmatrix} \\ &= \begin{bmatrix} 500/7 \\ 1000/7 \end{bmatrix}. \text{ So } \begin{bmatrix} 500 \\ 500 \end{bmatrix} = \frac{500}{7} \begin{bmatrix} 1 \\ -1 \end{bmatrix} + \frac{1000}{7} \begin{bmatrix} 3 \\ 4 \end{bmatrix} \end{aligned}$$

Second, find $\vec{x}_\infty = A^\infty \vec{x}_0$ (that is, find $\lim_{k \rightarrow \infty} A^k \vec{x}_0$). Again, show your work.

$$\begin{aligned} \text{So } A^k \vec{x}_0 &= A^k \left[\begin{bmatrix} 500/7 \\ -500/7 \end{bmatrix} + \begin{bmatrix} 3000/7 \\ 4000/7 \end{bmatrix} \right] \\ &= \left(\frac{-1}{6} \right)^k \begin{bmatrix} 500/7 \\ -500/7 \end{bmatrix} + 1^k \begin{bmatrix} 3000/7 \\ 4000/7 \end{bmatrix} \end{aligned}$$

which $\rightarrow \begin{bmatrix} 3000/7 \\ 4000/7 \end{bmatrix}$ as $k \rightarrow \infty$.

Notice: sum is 1000 (= 500 + 500) and the 3:4 ratio, as in the e-vector for e-value 1.

11 points 3. Consider matrix A which is row equivalent to matrix B :

$$A = \begin{bmatrix} 1 & -5 & 1 & 2 & -1 & 1 \\ 1 & -5 & 2 & 0 & -3 & 3 \\ 1 & -5 & 3 & -2 & 3 & 13 \\ 1 & -5 & 4 & -4 & 5 & 19 \end{bmatrix}, \quad B = \begin{bmatrix} 1 & -5 & 0 & 4 & 0 & -2 \\ 0 & 0 & 1 & -2 & 0 & 4 \\ 0 & 0 & 0 & 0 & 1 & 1 \\ 0 & 0 & 0 & 0 & 0 & 0 \end{bmatrix}$$

First, even though there are six columns, based on the dimensions of A , how do you know that $\dim \text{Col } A \leq 4$? $\dim \text{Col } A = \dim \text{Row } A \leq \# \text{rows}$

Find the following:

rank $A = 3$

3 pivots in cols. 1, 3, 5.

A basis for $\text{Col } A$:

Cols. 1, 3, 5 of A

A basis for $\text{Row } A$:

Rows 1, 2, 3 of A or B

A basis for $\text{Nul } A$:

Free variables: x_2

$$\begin{aligned} x_1 - 5x_2 + 4x_4 - 2x_6 &= 0 \\ x_3 - 2x_4 + 4x_6 &= 0 \\ x_5 + x_6 &= 0 \end{aligned}$$

x_4
 x_6

$$\Rightarrow \begin{pmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \\ x_5 \\ x_6 \end{pmatrix} = x_2 \begin{pmatrix} 5 \\ 1 \\ 0 \\ 0 \\ 0 \\ 0 \end{pmatrix} + x_4 \begin{pmatrix} -4 \\ 0 \\ 2 \\ 1 \\ 0 \\ 0 \end{pmatrix} + x_6 \begin{pmatrix} 2 \\ 0 \\ -4 \\ 0 \\ -1 \\ 1 \end{pmatrix}$$

Col. 2

9 points 4. Use Cramer's Rule to find x_2 in the linear system

$$\begin{cases} -x_1 + 2x_2 + 3x_3 = 0 \\ 3x_2 + 5x_3 = -2 \\ x_1 + 4x_2 = 0 \end{cases}$$

$$x_2 = \frac{\begin{vmatrix} -1 & 0 & 3 \\ 0 & -2 & 5 \\ 1 & 0 & 0 \end{vmatrix}}{\begin{vmatrix} -1 & 2 & 3 \\ 0 & 3 & 5 \\ 1 & 4 & 0 \end{vmatrix}} = \frac{\begin{vmatrix} -2 & -1 & 3 \\ 1 & 0 & 0 \end{vmatrix}}{\begin{vmatrix} -1 & 2 & 3 \\ 0 & 3 & 5 \\ 1 & 4 & 0 \end{vmatrix}} = \dots = \frac{6}{21}$$

15 points 5. Find the two eigenvalues and corresponding eigenvectors of $A = \begin{bmatrix} 2 & 2 \\ -3 & 7 \end{bmatrix}$.

Hint in factoring: $4 \cdot 5 = 20$

$$\begin{vmatrix} 2-\lambda & 2 \\ -3 & 7-\lambda \end{vmatrix} = (2-\lambda)(7-\lambda) + 6 = \lambda^2 - 9\lambda + 20 = (\lambda-4)(\lambda-5) = 0 \Rightarrow \lambda = 4, 5.$$

$\lambda = 4$: $A\vec{x} = 4\vec{x}$, i.e. $(A - 4I)\vec{x} = \vec{0}$ $\lambda = 5$

$$\begin{bmatrix} -2 & 2 \\ -3 & 3 \end{bmatrix} \sim \begin{bmatrix} 1 & -1 \\ 0 & 0 \end{bmatrix}$$

$$\begin{matrix} x_1 = x_2 \\ x_2 = x_2 \end{matrix} \Rightarrow \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = x_2 \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

$$\begin{bmatrix} -3 & 2 \\ -3 & 2 \end{bmatrix} \sim \begin{bmatrix} 1 & \frac{2}{3} \\ 0 & 0 \end{bmatrix}$$

$$\begin{matrix} x_1 = \frac{2}{3}x_2 \\ x_2 = x_2 \end{matrix} \Rightarrow \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = x_2 \begin{bmatrix} \frac{2}{3} \\ 1 \end{bmatrix}$$

Find matrices X and D so that $A = XDX^{-1}$.

$$A = \underbrace{\begin{bmatrix} 1 & \frac{2}{3} \\ 1 & 1 \end{bmatrix}}_X \underbrace{\begin{bmatrix} 4 & 0 \\ 0 & 5 \end{bmatrix}}_D \underbrace{\begin{bmatrix} 1 & \frac{2}{3} \\ 1 & 1 \end{bmatrix}^{-1}}_{X^{-1}}$$

How do you know that X is invertible?

It's cols. are lin. ind. (which was guaranteed since they correspond to two different e-values).

BTW, this has nothing to do with A 's e-values being 0 or not.